Matthew Jeung

510-821-4818 | matthewkimjeung@gmail.com

EDUCATION

University of Chicago

Chicago, IL

BS in Computer Science, Specialization in Machine Learning

Expected, 2026

- **GPA:** 3.85/4
- Honors: Quad Undergraduate Research Award (2x), Humanities UX Scholar, Jeff Metcalf Fellowship
- Relevant Coursework: Theory of Algorithms, Math Foundations for Machine Learning, Engineering Interactive Devices, Mobile Computing.
- Graduate Coursework: Introduction to Machine Learning, Robot Learning and Estimation

EXPERIENCE

Toyota Technological Institute at Chicago

June 2025 - Present

Robotics and AI Intern, Research Assistant, Robot Intelligence through Perception Lab

Chicago, IL

- Video Deep Learning: worked on autoencoder architecture for robot learning paper.
- Deep RL for Locomotion: trained multi-module locomotion policy in custom MuJoCo simulation.
- Extensive experience with PyTorch, parallelized GPU training, data processing, and visualization.
- Developed computer vision curriculum for HS robotic arm course.

Actuated Experience Lab

September 2023 – Present

Research Assistant

Chicago, IL

- Shape n' Swarm: Led research to control over 30 robots in real-time with hands and speech (UIST 2025).
- Co-led haptics research paper in industry collaboration with Sony Research (anonymized for CHI 2026 review).
- Developed physics simulation tools, robot-LLM integrations, React frontends, and path-planning logic for projects.

EduAvenues

June 2023 – September 2023

Software Engineering Intern

Remote

• Developed online standardized test simulator used by over 1100 paying users each year

PUBLICATIONS

• Jeung, M., et al. Shape n' Swarm: Hands-on, Shape-aware Generative Authoring with Swarm UI and LLMs. Accepted to UIST 2025 (ACM Symposium on User Interface Software and Technology).

Projects and Activities

UChicago Robotics Team

October 2024-Present

Combat Robotics Team

Chicago, IL

- $\bullet \ \ \text{Won MakeHarvard 2025 Most Sustainable Project with glove integrated with grocery sustainability feedback}$
- Designed 1-lb combat robot from scratch, developing Fusion 360, electronics, and prototyping skills

Ambient Song Selector for Spotify (iOS)

April 2024 - June 2024

• Developed ML-based Spotify extension to autoplay songs based on physical activity and environment

Phoenix Sustainability Initiative

September 2023 – May 2024

Green Data Team

Chicago, IL

• Performed Python data analysis and visualization on Chicago environmental justice and health conditions.

TECHNICAL SKILLS

Programming: Python, Java, Swift, C/C++, JavaScript, PyTorch, React, Processing

Electonics and Hardware: Microcontrollers, PCB design, Fusion 360, Rhino